

# SPATIAL DUAL MEMS GNSS/INS

Spatial Dual is a ruggedised miniature GPS aided inertial navigation system and AHRS that provides accurate position, velocity, acceleration and orientation under the most demanding conditions. It combines temperature calibrated accelerometers, gyroscopes, magnetometers and a pressure sensor with a dual antenna RTK GNSS receiver. These are coupled in a sophisticated fusion algorithm to deliver accurate and reliable navigation and orientation.

# PERFORMANCE

O.1 ° Roll and Pitch
O.1 ° Heading

8 mm RTK Positioning
 3 °/hr MEMS Gyroscope

1000 Hz Update Rate2000 g Shock Limit

# FEATURES



## **DUAL ANTENNA HEADING**

Spatial Dual features dual antenna moving baseline RTK. This allows it to provide highly accurate heading while both stationary and moving. It is an excellent choice for applications where magnetic

heading is not usable due to interference or where additional accuracy is required. An added benefit is the ability to accurately measure vehicle slip angle.



## RELIABILITY

Spatial Dual has been designed from the ground up for mission critical control applications where reliability is very important. It is built on top of a safety oriented real time operating system and all software is designed and tested to safety

standards with fault tolerance in mind. The hardware is protected from reverse polarity, overvoltage, surges, static and short circuits on all external interfaces. The GNSS contains RAIM, which excludes both malfunctioning, and tampered satellite signals.



#### **RTK GNSS RECEIVER**

Spatial Dual contains a triple frequency Trimble RTK GNSS receiver that provides up to 8mm accuracy positioning and supports all of the current and future satellite

navigation systems, including GPS, GLONASS, GALILEO and BeiDou. It also supports the Omnistar service for hassle free high accuracy positioning.



#### ADVANCED FILTER

Spatial Dual contains Advanced Navigation's revolutionary sensor fusion filter. The filter is more intelligent than the typical extended kalman filter and is able to extract significantly

more information from the data by making use of human inspired artificial intelligence. It was designed for control applications and has a high level of health monitoring and instability prevention to ensure stable and reliable data.



#### MINIATURE RUGGED ENCLOSURE

Spatial Dual's precision marine grade aluminium enclosure is waterproof and dirtproof to the IP67 standard and shockproof to 2000g, allowing it to be used in the most extreme

conditions. A sophisticated venting system allows the unit to measure air pressure whilst keeping water out. Its minimal size, weight and power requirements allow for easy integration into almost any system.



#### PERIPHERALS

Spatial Dual features four general purpose input output pins that support an extensive number of peripherals. Including odometer and wheel encoder inputs for ground

vehicles, external RTK GPS systems, NMEA input/output, event triggers and more. For an integration fee, custom peripheral devices can be added.

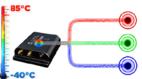


Spatial Dual contains a next generation battery backup system that allows it to hot start inertial navigation from its last position in 500 milliseconds and obtain a GNSS fix in approximately 3

seconds. The battery backup system lasts for the lifetime of the product and will provide backup for 48 hours without power. Advanced Navigation's Spatial series are the only GNSS/INS in the world to provide hot start inertial navigation.

#### NAVIGATION

Horizontal Position Accuracy	1.2 m
Vertical Position Accuracy	2.0 m
Horizontal Position Accuracy (with SBAS)	0.5 m
Vertical Position Accuracy (with SBAS)	0.8 m
Horizontal Position Accuracy (with RTK or Kinematica PPK)	0.008 m
Vertical Position Accuracy (with RTK or Kinematica PPK)	0.015 m
Velocity Accuracy	0.007 m/s
Roll & Pitch Accuracy	0.1 °
Heading Accuracy (1m Antenna Separation)	0.1 °
Roll & Pitch Accuracy (Kinematica post processing)	0.03 °
Heading Accuracy (Kinematica post processing)	0.06 °
Slip Accuracy	0.1 °
Heave Accuracy (whichever is greater)	5 % or 0.05 m
Range	Unlimited
Hot Start Time	500 ms
Internal Filter Rate	1000 Hz
Output Data Rate	Up to 1000Hz



### CALIBRATED DYNAMIC RANGING SENSORS

Spatial Dual contains very high performance MEMs inertial sensors. These are put through Advanced Navigation's intensive calibration

process to increase their performance further still and provide consistently accurate data over an extended temperature range of -40°C to 85°C. Advanced Navigation's custom calibration process is the only full sensor calibration that can provide dynamic ranging, allowing the user to select a sensor range for high accuracy or high accelerations on the fly. As part of this calibration, every Spatial Dual unit spends 8 hours in our specially built rotating temperature chamber.

#### GNSS

Model	Trimble BD982		
Supported Navigation Systems	GPS L1, L2, L5 GLONASS L1, L2 GALILEO E1, E5 BeiDou B1, B2		
Supported SBAS Systems	WAAS EGNOS MSAS GAGAN QZSS Omnistar HP/XP/G2 Trimble RTX		
Update Rate	20 Hz		
Hot Start First Fix	3 s		
Cold Start First Fix	30 s		
Horizontal Position Accuracy	1.2 m		
Horizontal Position Accuracy (with SBAS)	0.5 m		
Horizontal Position Accuracy (with RTK)	0.008 m		
Velocity Accuracy	0.007 m/s		
Timing Accuracy	20 ns		
Acceleration Limit	11 g		

#### COMMUNICATION

Interface	RS232 or RS422		
Speed	4800 to 2M baud		
Protocol	AN Packet Protocol or NMEA		
Peripheral Interface	2x GPIO and 1x Auxiliary RS232		
GPIO Level	5 V or RS232		
GPIO Functions	1PPS Odometer Stationary Pitot Tube NMEA input/output Novatel GNSS input Trimble GNSS input AN Packet Protocol input/output Packet Trigger Input Event Input		

# Hot Start Battery Capacity

HARDWARE Operating Voltage

Input Protection

Power Consumption (typical)

Hot Start Battery Charge Time	30 mins
Hot Start Battery Endurance	> 10 years
Operating Temperature	-40 °C to 85 °C
Environmental Protection	IP67 MIL-STD-810G
MTBF	> 50,000 hrs
Shock Limit	75 g
Dimensions	90 x 127 x 33 mm
Weight	285 grams

#### SENSORS

SENSOR	ACCELEROMETERS	GYROSCOPES	MAGNETOMETERS	PRESSURE
Range (dynamic)	± 2 g ± 4 g ± 16 g	± 250 °/s ± 500 °/s ± 2000 °/s	± 2 G ± 4 G ± 8 G	10 to 120 KPa
Bias Instability	20 µg	3 °/hr	-	10 Pa
Initial Bias	< 5 mg	< 0.2 °/s	-	< 100 Pa
Initial Scaling Error	< 0.06 %	< 0.04 %	< 0.07 %	-
Scale Factor Stability	< 0.06 %	< 0.05 %	< 0.09 %	-
Non-linearity	< 0.05 %	< 0.05 %	< 0.08 %	-
Cross-axis Alignment Error	< 0.05 °	< 0.05 °	< 0.05 °	-
Noise Density	100 µg/√Hz	0.004 °/s/√Hz	210 µg/√Hz	0.56 Pa/√Hz
Bandwidth	400 Hz	400 Hz	110 Hz	50 Hz

#### Australia Head Office +61 2 9099 3800 info@advancednavigation.com

mowadvancednavigation

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North American Office +1 407 680 9532 usasales@advancednavigation.com

9 to 36 V

> 48 hrs

-40 to 100 V 2.64 W

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